

Linear Algebra I

09/10/2023

1 Systems of linear equations

(1 + 6 + 3 + (1 + 6 + 3) = 20 pts)

Let a be a scalar. Consider the following system of linear equations in the unknowns x , y , and z :

$$\begin{aligned}x + 2y - 3z &= 4 \\3x - y + 5z &= -2 \\4x + y + (a^2 - 14)z &= a + 6.\end{aligned}$$

- Write down the corresponding augmented matrix .
- By performing elementary row operations, put the augmented matrix into row echelon form.
- Determine all values of a so that the system is consistent.
- For $a = 5$,
 - determine the *lead* and *free* variables.
 - put the augmented matrix into *reduced* row echelon form by performing elementary row operations.
 - find the solution set.

REQUIRED KNOWLEDGE: Gauss-Jordan elimination, row operations, reduced row echelon form, notions of lead/free variables.

SOLUTION:

1a: The corresponding augmented matrix is

$$\left[\begin{array}{cccc|c} 1 & 2 & -3 & 4 & 4 \\ 3 & -1 & 5 & -2 & -2 \\ 4 & 1 & a^2 - 14 & a + 6 & a + 6 \end{array} \right].$$

1b: To put the augmented matrix into row echelon form, we apply elementary row operations:

$$\begin{aligned} \left[\begin{array}{cccc|c} 1 & 2 & -3 & 4 & 4 \\ 3 & -1 & 5 & -2 & -2 \\ 4 & 1 & a^2 - 14 & a + 6 & a + 6 \end{array} \right] & \xrightarrow{\substack{\textcircled{2} \leftarrow \textcircled{2} - 3 \cdot \textcircled{1} \\ \textcircled{3} \leftarrow \textcircled{3} - 4 \cdot \textcircled{1}}} \left[\begin{array}{cccc|c} 1 & 2 & -3 & 4 & 4 \\ 0 & -7 & 14 & -14 & -14 \\ 0 & -7 & a^2 - 2 & a - 10 & a - 10 \end{array} \right] \\ \left[\begin{array}{cccc|c} 1 & 2 & -3 & 4 & 4 \\ 0 & -7 & 14 & -14 & -14 \\ 0 & -7 & a^2 - 2 & a - 10 & a - 10 \end{array} \right] & \xrightarrow{\textcircled{3} \leftarrow \textcircled{3} - 1 \cdot \textcircled{2}} \left[\begin{array}{cccc|c} 1 & 2 & -3 & 4 & 4 \\ 0 & -7 & 14 & -14 & -14 \\ 0 & 0 & a^2 - 16 & a + 4 & a + 4 \end{array} \right] \\ \left[\begin{array}{cccc|c} 1 & 2 & -3 & 4 & 4 \\ 0 & -7 & 14 & -14 & -14 \\ 0 & 0 & a^2 - 16 & a + 4 & a + 4 \end{array} \right] & \xrightarrow{\textcircled{2} \leftarrow -\frac{1}{7} \cdot \textcircled{2}} \left[\begin{array}{cccc|c} 1 & 2 & -3 & 4 & 4 \\ 0 & 1 & -2 & 2 & 2 \\ 0 & 0 & a^2 - 16 & a + 4 & a + 4 \end{array} \right] \end{aligned}$$

Now, we distinguish two cases: $a^2 - 16 \neq 0$ or $a^2 - 16 = 0$.

If $a^2 - 16 \neq 0$, then $a \neq 4$ and one more elementary row operation puts the matrix into row echelon form:

$$\left[\begin{array}{cccc|c} 1 & 2 & -3 & 4 & 4 \\ 0 & 1 & -2 & 2 & 2 \\ 0 & 0 & a^2 - 16 & a + 4 & a + 4 \end{array} \right] \xrightarrow{\textcircled{3} \leftarrow \frac{1}{a^2 - 16} \cdot \textcircled{3}} \left[\begin{array}{cccc|c} 1 & 2 & -3 & 4 & 4 \\ 0 & 1 & -2 & 2 & 2 \\ 0 & 0 & 1 & \frac{1}{a-4} & \frac{1}{a-4} \end{array} \right].$$

If $a^2 - 16 = 0$, then either $a = -4$ or $a = 4$. For $a = -4$, the matrix is already in the row echelon form:

$$\begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & 1 & -2 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

For $a = 4$, one more elementary row operation yields the row echelon form:

$$\begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & -7 & 14 & -14 \\ 0 & 0 & 0 & 8 \end{bmatrix} \xrightarrow{\textcircled{3} \leftarrow \frac{1}{8} \cdot \textcircled{3}} \begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & 1 & -2 & 2 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

1c: From (1b), we see that the system is consistent if and only if $a \neq 4$.

1d(i): For $a = 5$, we obtained in (1b) the following row echelon matrix.

$$\begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & 1 & -2 & 2 \\ 0 & 0 & 1 & 1 \end{bmatrix}.$$

Then, there no free variables and hence all variables are free.

1d(ii): To obtain the reduced row echelon form, we apply elementary row operations:

$$\begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & 1 & -2 & 2 \\ 0 & 0 & 1 & 1 \end{bmatrix} \xrightarrow{\begin{array}{l} \textcircled{2} \leftarrow \textcircled{2} + 2 \cdot \textcircled{3} \\ \textcircled{1} \leftarrow \textcircled{1} + 3 \cdot \textcircled{3} \end{array}} \begin{bmatrix} 1 & 2 & 0 & 7 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 0 & 7 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & 1 \end{bmatrix} \xrightarrow{\textcircled{1} \leftarrow \textcircled{1} - 2 \cdot \textcircled{2}} \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & 1 \end{bmatrix}.$$

1d(iii): The unique solution is $x = -1$, $y = 4$, and $z = 1$.

2 Matrix multiplication

(5 + 10 = 15 pts)

Let $A \in \mathbb{F}^{p \times q}$ and $B \in \mathbb{F}^{q \times p}$. Prove or disprove the statements:

(a) $\det(AB) = \det(BA)$

(b) $\operatorname{tr}(AB) = \operatorname{tr}(BA)$ (For $M \in \mathbb{F}^{m \times m}$, $\operatorname{tr}(M) := \sum_{k=1}^m [M]_{kk}$.)

REQUIRED KNOWLEDGE: Matrix multiplication, determinant.

SOLUTION:

2a: We know that $\det(AB) = \det(BA)$ if $p = q$. When $p \neq q$, however, this relation does not hold in general. A counter example can be obtained by taking

$$A = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \text{and} \quad B = [1 \quad 1].$$

Indeed, these choices yield

$$AB = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \quad \text{and} \quad BA = 2.$$

Note that $\det(AB) = 0 \neq 2 = \det(BA)$.

2b: From the definition of the matrix multiplication, we know that

$$[AB]_{ij} = \sum_{k=1}^q [A]_{ik} [B]_{kj} \quad \text{and} \quad [BA]_{ij} = \sum_{\ell=1}^p [B]_{i\ell} [A]_{\ell j}.$$

Therefore, we have

$$\operatorname{tr}(AB) = \sum_{i=1}^p [AB]_{ii} = \sum_{i=1}^p \sum_{k=1}^q [A]_{ik} [B]_{ki} = \sum_{k=1}^q \sum_{i=1}^p [B]_{ki} [A]_{ik} = \sum_{k=1}^q [BA]_{kk} = \operatorname{tr}(BA).$$

Let $M(n) \in \mathbb{R}^{n \times n}$ be given by

$$[M(n)]_{ij} = \begin{cases} 1 & \text{if } |i - j| \leq 1 \\ 0 & \text{otherwise.} \end{cases}$$

For instance,

$$M(5) = \begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix}.$$

- (a) Compute the determinant of $M(n)$ for $n \in \{1, 2, 3\}$.
- (b) Find real numbers a, b such that $\det(M(n+2)) = a \det(M(n+1)) + b \det(M(n))$ for all $n \geq 1$.

REQUIRED KNOWLEDGE: Matrix multiplication, nonsingular matrices, and inverse matrix.

SOLUTION:

3a: We have

$$M(1) = 1, \quad M(2) = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}, \quad \text{and} \quad M(3) = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}.$$

Then, we see that $\det(M(1)) = 1$ since $M(1)$ is a scalar, $\det(M(2)) = 0$ since $M(2)$ has two identical rows, and $\det(M(3)) = 1 - 1 - 1 = -1$ due to Sarrus' rule.

3b: Let $M = M(n+2)$. The cofactor expansion of the determinant M along the first row yields:

$$\det(M(n+2)) = \det(M_{11}) - \det(M_{21}).$$

Note that M_{11} is nothing but $M(n+1)$ and the first column of M_{12} is the first column of I_{n+1} . By the cofactor expansion of M_{12} along its first column, we see that $\det(M_{12}) = \det((M_{12})_{11})$. Note that matrix $(M_{12})_{11}$ is the matrix obtained from M by deleting the first two rows and columns. Therefore, we see that $\det(M_{12}) = \det(M(n))$. Hence, we obtain

$$\det(M(n+2)) = \det(M(n+1)) - \det(M(n))$$

showing that $a = 1$ and $b = -1$.

Let a, b, c, d be scalars and $M \in \mathbb{F}^{m \times m}$. Consider the matrix

$$N = \begin{bmatrix} aM & bM \\ cM & dM \end{bmatrix}.$$

- (a) Show that N is nonsingular if and only if $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ and M are nonsingular.
- (b) Suppose that $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ and M are nonsingular. Find the inverse of N .

REQUIRED KNOWLEDGE: Nonsingularity and partitioned matrices.

SOLUTION:

4a: To prove the ‘only if’ part, let e, f be such that $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} e \\ f \end{bmatrix} = \mathbf{0}_2$. Then, we have

$$ae + bf = 0 \quad \text{and} \quad ce + df = 0.$$

Now, let \mathbf{x} be a nonzero vector in \mathbb{F}^m . Note that

$$N \begin{bmatrix} e\mathbf{x} \\ f\mathbf{x} \end{bmatrix} = \begin{bmatrix} (ae + bf)\mathbf{x} \\ (ce + df)\mathbf{x} \end{bmatrix} = \mathbf{0}_{2m}$$

Since N is nonsingular, we can conclude that $e\mathbf{x} = f\mathbf{x} = \mathbf{0}_m$. As \mathbf{x} is a nonzero vector, we see that $e = f = 0$. Consequently, the matrix $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is nonsingular. What remains to be proven is the nonsingularity of M . Let $\mathbf{x} \in \mathbb{F}^m$ be such that $M\mathbf{x} = \mathbf{0}_m$. Note that

$$N \begin{bmatrix} \mathbf{x} \\ \mathbf{x} \end{bmatrix} = \mathbf{0}_{2m}.$$

From the nonsingularity of N , it follows that $\mathbf{x} = \mathbf{0}_m$ and hence M is nonsingular.

To prove the ‘if’ part, let $\mathbf{x}, \mathbf{y} \in \mathbb{F}^m$ be such that

$$N \begin{bmatrix} \mathbf{x} \\ \mathbf{y} \end{bmatrix} = \mathbf{0}_{2m}.$$

Since

$$N \begin{bmatrix} \mathbf{x} \\ \mathbf{y} \end{bmatrix} = \begin{bmatrix} aM\mathbf{x} + bM\mathbf{y} \\ cM\mathbf{x} + dM\mathbf{y} \end{bmatrix},$$

we see that

$$aM\mathbf{x} + bM\mathbf{y} = \mathbf{0}_m \tag{1}$$

$$cM\mathbf{x} + dM\mathbf{y} = \mathbf{0}_m. \tag{2}$$

If we multiply both sides of (1) by d , those of (2) by $-b$ and add them up, we obtain

$$(ad - bc)M\mathbf{x} = \mathbf{0}_m. \tag{3}$$

Since $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is nonsingular, its determinant $ad - bc \neq 0$, it then follows from (3) that $M\mathbf{x} = \mathbf{0}_m$. As M is nonsingular, we can conclude that $\mathbf{x} = \mathbf{0}_m$. By proceeding in a similar fashion, one can multiply (1) by $-c$ and (2) by a to obtain $(ad - bc)M\mathbf{y} = \mathbf{0}_m$. This would lead to $\mathbf{y} = \mathbf{0}_m$ and proves that N is nonsingular.

4b: Let $U, V, W, Z \in \mathbb{F}^{m \times m}$ be such that

$$N^{-1} = \begin{bmatrix} U & V \\ W & Z \end{bmatrix}.$$

By using $NN^{-1} = I_{2m}$, we see that

$$aMU + bMW = I_m \tag{4}$$

$$aMV + bMZ = 0_{m,m} \tag{5}$$

$$cMU + dMW = 0_{m,m} \tag{6}$$

$$cMV + dMZ = I_m \tag{7}$$

From (4) and (6), we see that $d(aMU + bMW) - b(cMU + dMW) = dI_m$, or equivalently $(ad - bc)MU = dI_m$. Since $ad - bc \neq 0$ due to the nonsingularity of $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ and M is nonsingular, we obtain

$$U = \frac{d}{ad - bc} M^{-1}.$$

Again from (4) and (6), we see that $-c(aMU + bMW) + a(cMU + dMW) = -cI_m$. Then, we have

$$W = -\frac{c}{ad - bc} M^{-1}.$$

Similarly, it follows from (5) and (7) that $-bI_m = d(aMV + bMZ) - b(cMV + dMZ) = (ad - bc)MV$ and $aI_m = -c(aMV + bMZ) + a(cMV + dMZ) = (ad - bc)MZ$. These result in

$$V = -\frac{b}{ad - bc} M^{-1} \quad \text{and} \quad Z = \frac{a}{ad - bc} M^{-1}.$$

Consequently, we have

$$N^{-1} = \frac{1}{ad - bc} \begin{bmatrix} dM^{-1} & -bM^{-1} \\ -cM^{-1} & aM^{-1} \end{bmatrix}.$$
